

Proposition 6.2 (Class 12)

June 19, 2015

```
# parametrize the Hadamard square root of rank five

#[
# [ 1, 0, 0, 0, 0, 1, 1, 1],
# [ y1, 0, 0, 0, 1, 1, 0, 0],
# [ 0, 1, 0, 0, 0, 1, y12, y13],
# [ 0, y4, 0, 0, y11, 1, 0, 0],
# [ y2, 0, 1, 0, 0, 0, 1, 0],
# [ 0, y5, y7, 0, 0, 0, 1, 0],
# [ y3, 0, 0, 1, 0, 0, 0, 1],
# [ 0, y6, 0, y9, 0, 0, 0, 1],
# [ 0, 0, y8, y10, 1, 0, 0, 0]]

R.<y1,y2,y3,y4,y5,y6,y7,y8,y9,y10,y11,y12,y13>=QQ [];

M = matrix(R,[
[ 1, 0, 0, 0, 0, 1, 1, 1],
[ y1, 0, 0, 0, 1, 1, 0, 0],
[ 0, 1, 0, 0, 0, 1, y12, y13],
[ 0, y4, 0, 0, y11, 1, 0, 0],
[ y2, 0, 1, 0, 0, 0, 1, 0],
[ 0, y5, y7, 0, 0, 0, 1, 0],
[ y3, 0, 0, 1, 0, 0, 0, 1],
[ 0, y6, 0, y9, 0, 0, 0, 1],
[ 0, 0, y8, y10, 1, 0, 0, 0]]); M

J=ideal(M.minors(6));
JJ=ideal(y1*y2*y3*y4*y5*y6*y7*y8*y9*y10*y11*y12*y13)
KK=J.saturation(JJ)
KK
[ 1 0 0 0 0 1 1 1]
[ y1 0 0 0 1 1 0 0]
[ 0 1 0 0 0 1 y12 y13]
[ 0 y4 0 0 y11 1 0 0]
[ y2 0 1 0 0 0 1 0]
[ 0 y5 y7 0 0 0 1 0]
[ y3 0 0 1 0 0 0 1]
[ 0 y6 0 y9 0 0 0 1]
[ 0 0 y8 y10 1 0 0 0]
```

(Ideal (y13 - 1, y12 - 1, y11 - 1, y10 - 1, y9 - 1, y8 - 1, y7 - 1, y4 + y5 + y6 - 1, y3 - y6, y2 - y5, y1 + y5 + y6 - 1) of Multivariate Polynomial Ring in y1, y2, y3, y4, y5, y6, y7, y8, y9, y10, y11, y12, y13 over Rational Field, 1)

```
# y13 - 1, y12 - 1, y11 - 1, y10 - 1, y9 - 1, y8 - 1, y7 - 1, y3 - y6, y2\
- y5
```

```
R.<y1,y2,y3>=QQ[];
```

```
M = matrix(R,[
[ 1, 0, 0, 0, 0, 1, 1, 1],
[ y1, 0, 0, 0, 1, 1, 0, 0],
[ 0, 1, 0, 0, 0, 1, 1, 1],
[ 0, y1, 0, 0, 1, 1, 0, 0],
[ y2, 0, 1, 0, 0, 0, 1, 0],
[ 0, y2, 1, 0, 0, 0, 1, 0],
[ y3, 0, 0, 1, 0, 0, 0, 1],
[ 0, y3, 0, 1, 0, 0, 0, 1],
[ 0, 0, 1, 1, 1, 0, 0, 0]]); M
```

```
J=ideal(M.minors(6));
```

```
JJ=ideal(y1*y2*y3)
```

```
KK=J.saturation(JJ)
```

```
KK
```

```
[ 1 0 0 0 0 1 1 1]
[y1 0 0 0 1 1 0 0]
[ 0 1 0 0 0 1 1 1]
[ 0 y1 0 0 1 1 0 0]
[y2 0 1 0 0 0 1 0]
[ 0 y2 1 0 0 0 1 0]
[y3 0 0 1 0 0 0 1]
[ 0 y3 0 1 0 0 0 1]
[ 0 0 1 1 1 0 0 0]
```

(Ideal (y1 + y2 + y3 - 1) of Multivariate Polynomial Ring in y1, y2, y3 over Rational Field, 0)

```
# y1 + y2 + y3 - 1
```

```
# the Hadamard square root and the slack matrix can be parametrized in \
the following way
```

```
M = matrix(R,[
[ 1, 0, 0, 0, 0, 1, 1, 1],
[ y1, 0, 0, 0, 1, 1, 0, 0],
[ 0, 1, 0, 0, 0, 1, 1, 1],
[ 0, y1, 0, 0, 1, 1, 0, 0],
[ y2, 0, 1, 0, 0, 0, 1, 0],
[ 0, y2, 1, 0, 0, 0, 1, 0],
```

```

[ (1-y1-y2), 0, 0, 1, 0, 0, 0, 1],
[ 0, (1-y1-y2), 0, 1, 0, 0, 0, 1],
[ 0, 0, 1, 1, 1, 0, 0, 0]]);

# thus y1^2=x1, y2^2=x2, (1-y1-y2)^2=1-x1-x2

%macaulay2
R = QQ[y1,y2,x1,x2,MonomialOrder => Eliminate 2];
I = ideal(y1^2-x1,y2^2-x2,(1-y1-y2)^2-1+x1+x2);
G = selectInSubring(1,gens gb I);
newpoly = G_0_0;
toString factor newpoly
Ideal of R

      1      1
Matrix R <--- R

(x1^4+2*x1^3*x2+3*x1^2*x2^2+2*x1*x2^3+x2^4-2*x1^3-2*x2^3+x1^2-2*x1*x2+x2^2)

```